

ESE 617/MEAM 613: Nonlinear Systems & Control (Fall 2019)

Extra Homework

Due on 12/2/2019, 9 a.m., in class

1. **Sensitivity Equation:** Consider the scalar system

$$\dot{x} = -\lambda x^3$$

- 1.1 Write down the sensitivity equation for the parameter $\lambda > 0$. (3 points)
- 1.2 Compute the sensitivity function in closed form. You may use MATLAB to check your answer but make sure to include hand derivation of the solution. (5 points)
- 1.3 What is the first-order approximation

$$x(t; \lambda) = x(t; \lambda_0) + S(t)(\lambda - \lambda_0)$$

at $\lambda_0 = 2$? (2 points)

2. **Lyapunov Stability:** Prove that the system

$$\begin{aligned}\dot{x}_1 &= -x_2^3 \\ \dot{x}_2 &= x_1 - x_2\end{aligned}$$

is globally asymptotically stable by (both of)

- 2.1 the La Salle's invariance principle; (5 points)
- 2.2 finding a Lyapunov function with negative definite \dot{V} . (5 points)
Hint: For 2.2, you may append your V from 2.1 by a general quadratic term and find the appropriate coefficients.

3. **Chetaev's Theorem:** Prove that the following system

$$\begin{aligned}\dot{x}_1 &= x_2 + x_1^3 + 3x_1x_2^2 \\ \dot{x}_2 &= -x_1 + x_2^3 + 3x_2x_1^2\end{aligned}$$

is unstable (3 points). Include an illustration of the set U from which the solutions can escape the origin (2 points).

4. **La Salle's Invariance Principle:** Consider the system

$$\begin{aligned}\dot{x}_1 &= x_2 + x_1x_3 \\ \dot{x}_2 &= -x_1 - x_2 + x_2x_3 \\ \dot{x}_3 &= -x_1^2 - x_2^2\end{aligned}$$

Which of the state globally variables converge to zero and which may not? Why? (5 points)

5. **Averaging Theory:** Consider the system

$$\begin{aligned}\dot{x}_1 &= \sin \omega t [x_1 + \sin \omega t] [x_2 + \cos \omega t - x_1 - \sin \omega t] \\ \dot{x}_2 &= \cos \omega t [x_2 + \cos \omega t] [x_1 + \sin \omega t - x_2 - \cos \omega t]\end{aligned}$$

Show that for sufficiently large $\omega > 0$, the system has an exponentially stable limit cycle in an $O(1/\omega)$ neighborhood of the origin. (10 points)