

# ESE 617/MEAM 613: Nonlinear Systems & Control (Fall 2019)

## Homework #11

Due on 11/27/2019, 9 a.m., in class

1. **Input-Output Feedback Linearization:** Consider the system

$$\begin{aligned}\dot{x}_1 &= -x_1 + x_2 - x_3 \\ \dot{x}_2 &= -x_1 x_3 - x_2 + u \\ \dot{x}_3 &= -x_1 + u \\ y &= x_3\end{aligned}$$

- 1.1 What is the system's relative degree? (3 points)
- 1.2 Is the system input-output feedback linearizable? Why? (2 points)
- 1.3 Find the feedback control input  $u(x)$  that makes the input-output relationship linear. (5 points)
- 1.4 What is the system's zero dynamics? Is it minimum phase? (5 points)
- 1.5 Find the change of coordinates that puts the system in normal form. (5 points)  
*Hint:* For the last part, apart from  $\xi$  whose choice is trivial, you need to find  $\eta_1$  and  $\eta_2$  both of which have to satisfy  $\frac{\partial \eta_i}{\partial x} g(x) = 0$ ,  $i = 1, 2$ . Don't look for complicated functions. There are very simple  $\eta_i$  that satisfy this, just make sure that  $\xi$ ,  $\eta_1$ , and  $\eta_2$  are linearly independent (otherwise they won't make a "change of variables", right?!)

2. **Functional Distributions:** Consider the distribution

$$\Delta = \text{span}\{f_1, f_2\}$$

where

$$f_1(x) = \begin{bmatrix} x_1 \\ 1 \\ 0 \\ x_3 \end{bmatrix}, \quad f_2(x) = \begin{bmatrix} e^{-x_2} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- 2.1 Is  $\Delta$  non-singular? Why? (3 points)
- 2.2 Is  $\Delta$  involutive? Why? (5 points)