

ESE 617/MEAM 613: Nonlinear Systems & Control (Fall 2019)

Homework #4

Due on 10/9/2019, 9 a.m., in class

1. **Lyapunov Stability.** Consider the system

$$\begin{aligned}\dot{x} &= y \\ \dot{y} &= -\frac{x}{1+y^2}\end{aligned}$$

Prove that the origin is stable (5 points).

Hint: Seek a Lyapunov function of the form $V(x, y) = \phi(x) + \psi(y)$.

2. **Chetaev's Theorem.** Consider the system

$$\begin{aligned}\dot{x} &= |x|x + xy\sqrt{|y|} \\ \dot{y} &= -y + |x|\sqrt{|y|}\end{aligned}$$

Show that the origin is unstable. Plot the set U in Chetaev's theorem (by hand or MATLAB) (5 points).

3. **La Salle's Invariance Principle.** Consider the system

$$\begin{aligned}\dot{x} &= -x + yx + z \cos(x) \\ \dot{y} &= -x^2 \\ \dot{z} &= -x \cos(x)\end{aligned}$$

- a) Find all the equilibria and determine the stability property of the origin (3 points).
- b) Prove that $\lim_{t \rightarrow \infty} x(t) = 0$ (2 points).
- c) Prove that $\lim_{t \rightarrow \infty} z(t) = 0$ (2 points).