The Fundamentals of Operating Systems

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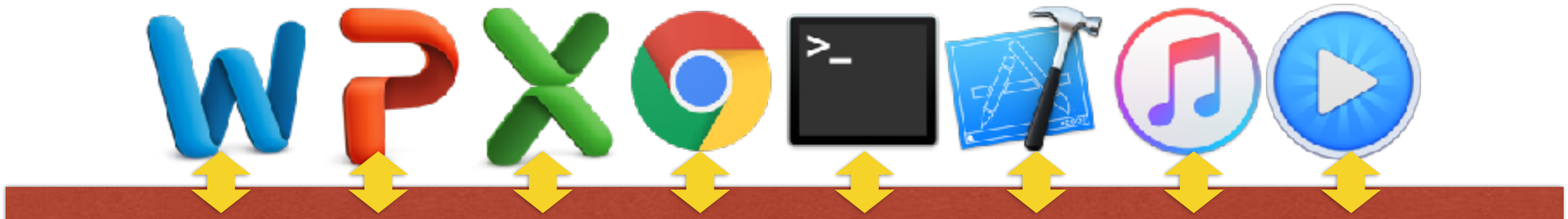
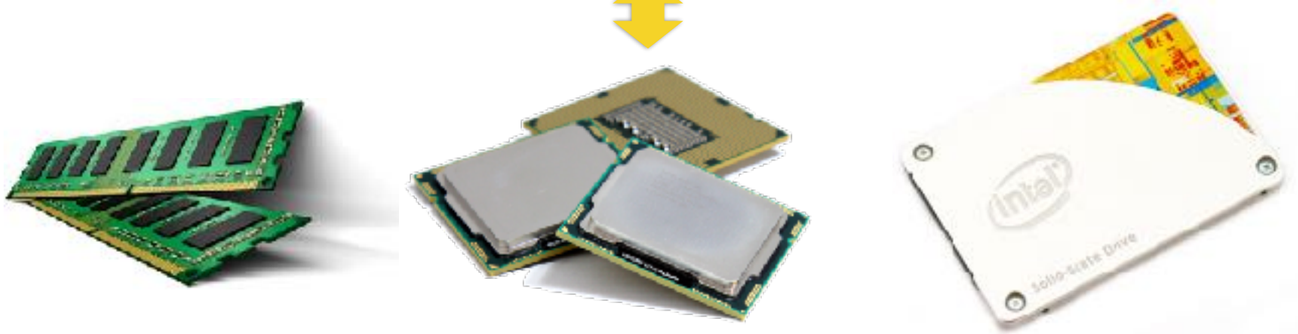
Outline

- Operating systems: virtualizing computers
- Process: the most important abstraction in modern OSs
- Restricted operations: kernel and user modes

The goal of an OS



Operating System

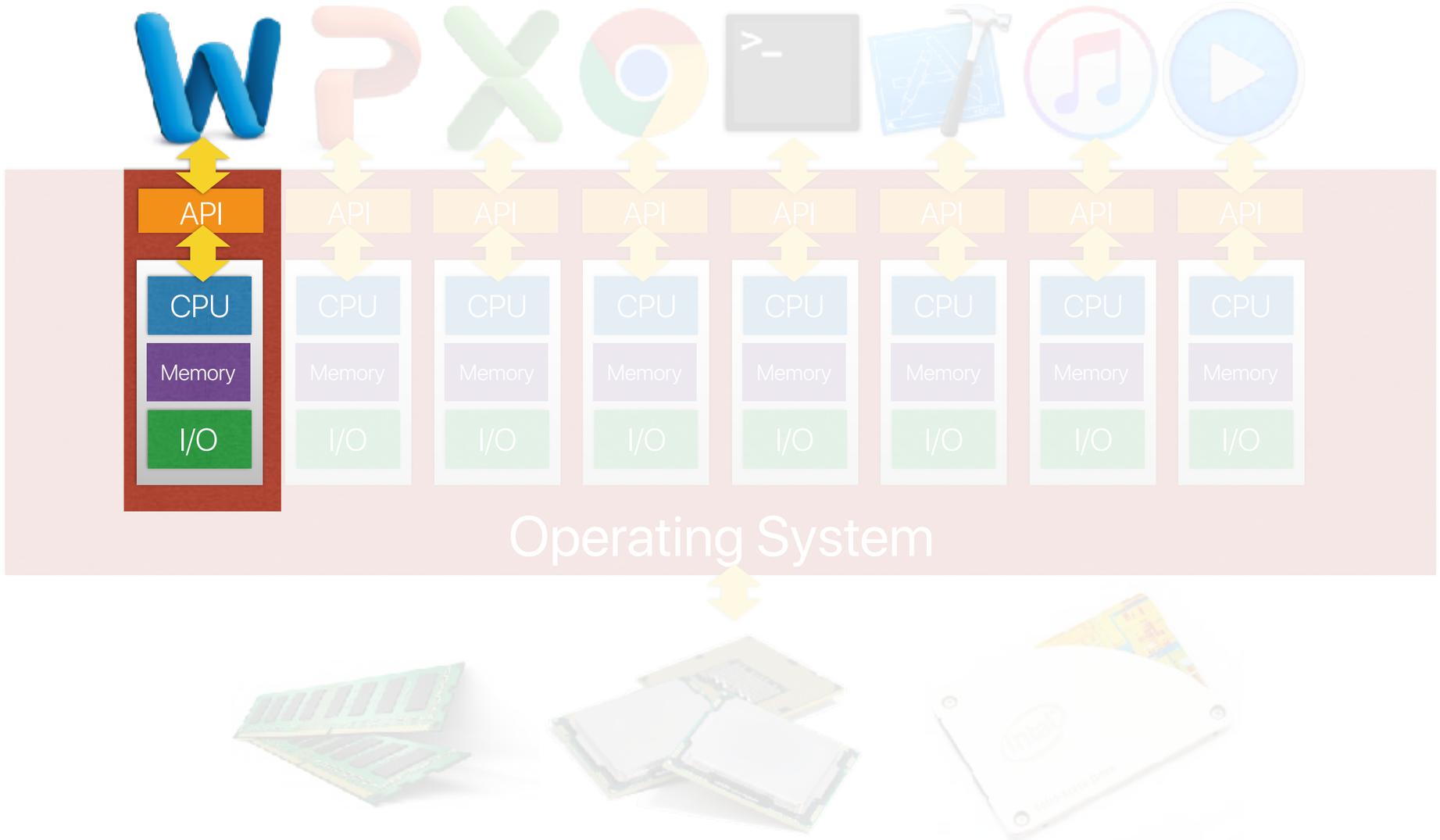


Operating systems: virtualizing computers

The idea: virtualization

- The operating system presents an illusion of a virtual machine to each running program and maintains architectural states of a von Neumann machine
  - Processor
  - Memory
  - I/O
- Each virtualized environment accesses architectural facilities through some sort of application programming interface (API)
- Dynamically map those virtualized resources into physical resources

The idea of an OS: virtualization



Latency v.s. Throughput

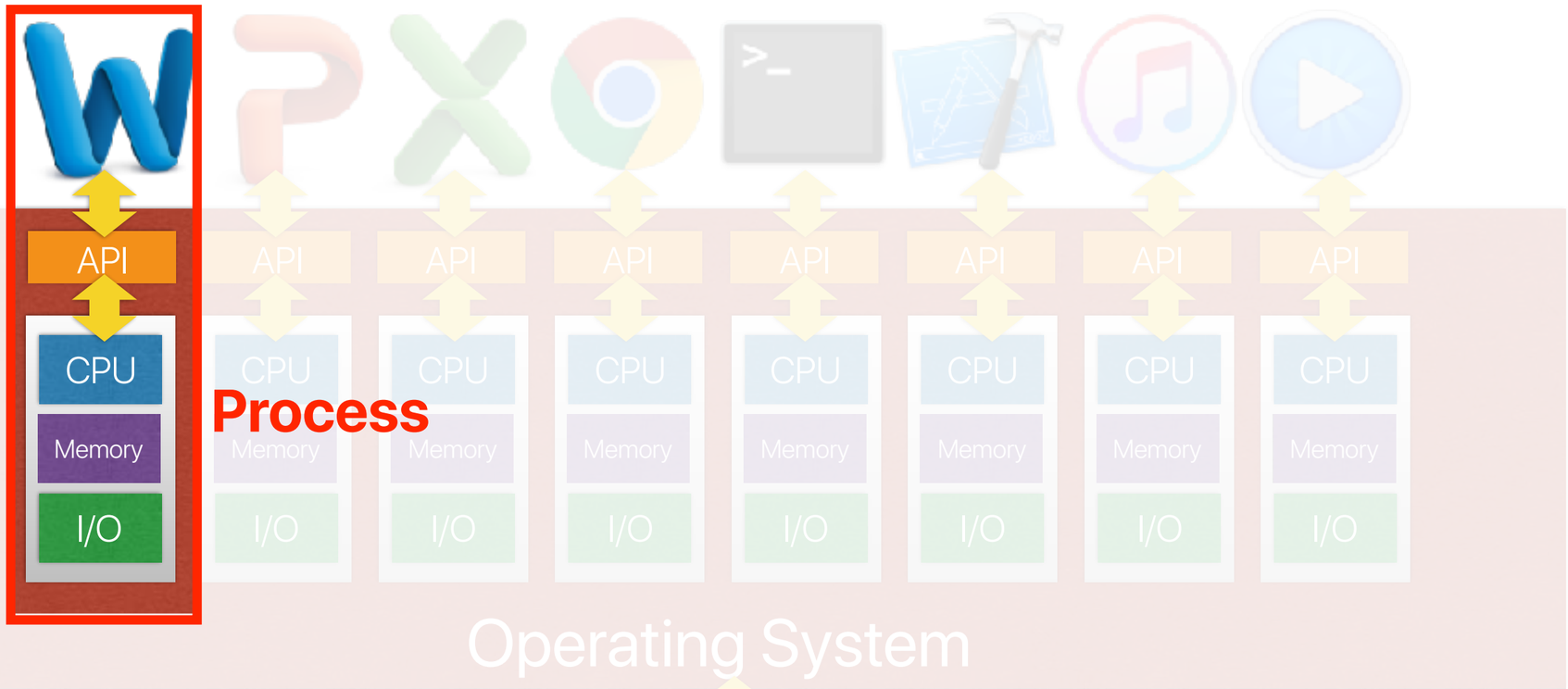
- A 4K movie clip using H.265 coding takes **70GB** in storage
- If you want to transfer a total of 2 Peta-Byte video clips (roughly 29959 movies) from UCSD
  - 100 miles from UCR
  - Assume that you have a **100Gbps** ethernet
    - Throughput: 100 Gbits per second
    - 2 Peta-byte (16 Peta-bits) over 167772 seconds = 1.94 Days
    - Latency: first 70GB (first movie) in 6 seconds

Or …

	Toyota Prius	10Gb Ethernet
	100 miles from UCSD 75 MPH on highway! 50 MPG Max load: 374 kg = 2,770 hard drives (2TB per drive) = 5.6 PB	
Throughput/ bandwidth	**450GB/sec**	100 Gb/s or 12.5GB/sec
latency	3.5 hours	2 Peta-byte over 167772 seconds = 1.94 Days
response time	You see **nothing** in the first 3.5 hours	You can start watching the first movie as soon as you get a frame!

Process: the most important abstraction in modern operating systems

The idea of an OS: virtualization



Processes

- The **most important abstraction** in modern operating systems.
- A process abstracts the underlying computer.
- A process is a **running program —** a dynamic entity of a program.
  - Program is a static file/combination of instructions
  - Process = program + states
  - The states evolves over time
- A process may be dynamically switched out/back during the execution

Virtualization

- The operating system presents an **illusion** of a **virtual machine** to each running program — **process**
  - Each virtual machine contains architectural states of a von Neumann machine
    - Processor
    - Memory
    - I/O
- Each virtualized environment accesses architectural facilities through some sort of application programming interface (API) — **system calls**
- Dynamically map those virtualized resources into physical resources — **policies, mechanisms**

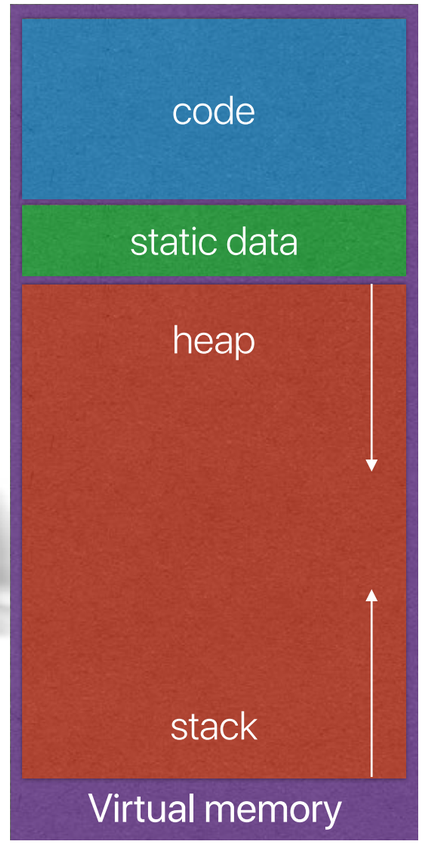
Demo: Virtualization

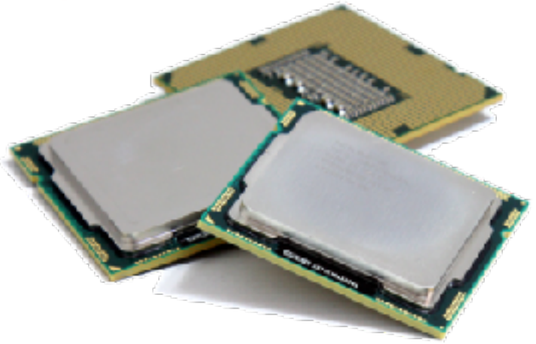
- We use the `getcpu` system call to identify the processor and node on which the calling process (can be a thread as well) is currently running and writes them into the integers pointed to by the cpu and node arguments.

Demo: Virtualization

- Some processes may use the same processor
- Each process has the same address for variable a, but different values.
- You may see the content of a compiled program using objdump

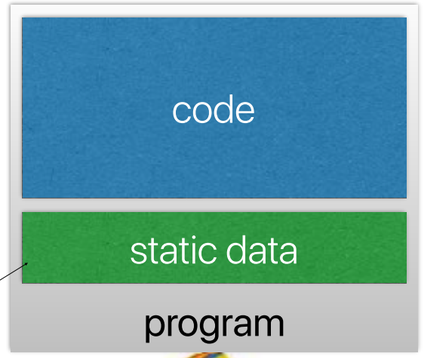
What happens when creating a process





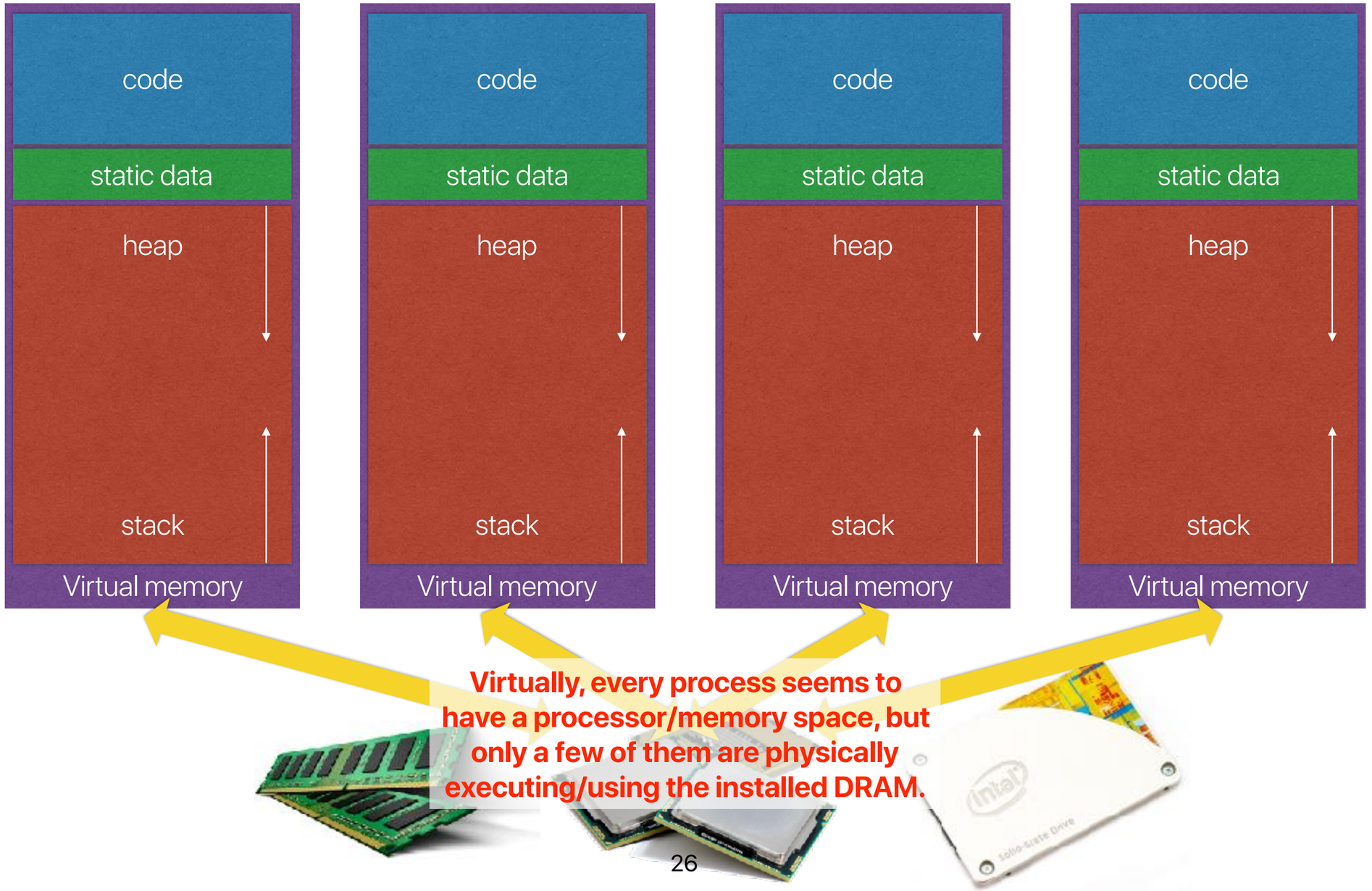
Dynamic allocated data: `malloc()`

Local variables,
arguments



Linux contains a .bss section
for uninitialized global variables

The illusion provided by processes



What the OS must track for a process?

- Which of the following information does the OS need to track for each process?
  A. Stack pointer
  B. Program counter
  C. Process state
  D. Registers
  E. All of the above

  - You also need to keep other process information like an unique process id, process states, I/O status, and etc…

Process control block

- OS has a PCB for each process
- Sometimes called Task Controlling Block, Task Struct, or Switchframe
- The data structure in the operating system kernel containing the information needed to manage a particular process.
- The PCB is the manifestation of a process in an operating system

Example: `struct task_struct` in Linux

```
struct task_struct {
        volatile long state;    /* -1 unrunnable, 0 runnable, >0 stopped */
        void *stack;
        atomic_t usage;
        unsigned int flags;     /* per process flags, defined below */
        unsigned int ptrace;
        int on_rq;
        int prio, static_prio, normal_prio;
        const struct sched_class *sched_class;
        struct sched_entity se;
        struct sched_rt_entity rt;
        unsigned int policy;
        int nr_cpus_allowed;
        cpumask_t cpus_allowed;
        pid_t pid;
        struct task_struct __rcu *real_parent;
        struct task_struct __rcu *parent;
        struct list_head children;
        struct list_head sibling;
        ……
        struct list_head tasks;
        ……
        struct mm_struct *mm, *active_mm;
        ……
/* CPU-specific state of this task */
        struct thread_struct thread;
}
```

Process state

Process ID

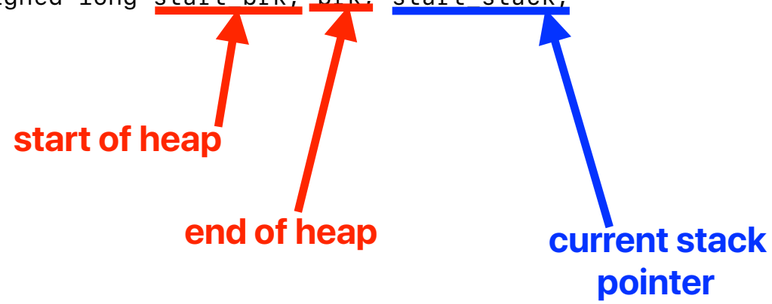
Virtual memory pointers

Low-level architectural states

- You may find this struct in /usr/src/linux-headers-x.x.x-xx/include/linux/sched.h

Memory pointers in `struct mm_struct`

```
struct mm_struct {
        struct vm_area_struct * mmap;           /* list of VMAs */
        ...
        unsigned long start_code, end_code, start_data, end_data;
        unsigned long start_brk, brk, start_stack;
        ...
};
```



Processor states in `struct thread_struct`

```
struct thread_struct {
        struct desc_struct tls_array[GDT_ENTRY_TLS_ENTRIES];
        unsigned long           sp0;
        unsigned long           sp;
#ifdef CONFIG_X86_32
        unsigned long           sysenter_cs;
#else
        unsigned short          es;
        unsigned short          ds;
        unsigned short          fsindex;
        unsigned short          gsindex;
#endif
#ifdef CONFIG_X86_32
        unsigned long           ip;
#endif
#ifdef CONFIG_X86_64
        unsigned long           fs;
#endif
        unsigned long           gs;
        struct perf_event       *ptrace_bps[HBP_NUM];
        unsigned long           debugreg6;
        unsigned long           ptrace_dr7;
        unsigned long           cr2;
        unsigned long           trap_nr;
        unsigned long           error_code;
#ifdef CONFIG_VM86
        struct vm86             *vm86;
#endif
        unsigned long           *io_bitmap_ptr;
        unsigned long           iopl;
        unsigned                io_bitmap_max;
        struct fpu              fpu;
    };
```

Some x86 Register values

Program counter

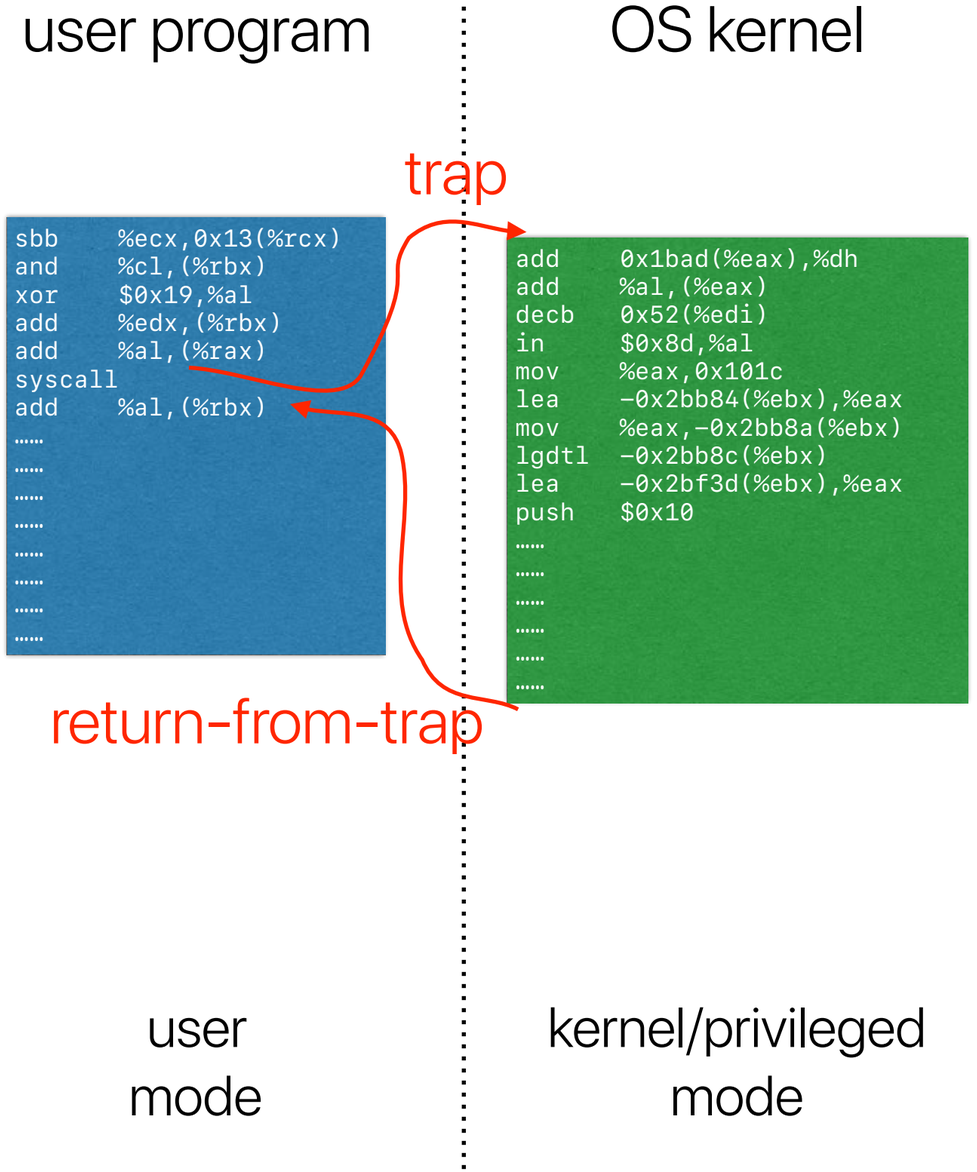
Restricted operations: kernel and user modes

Restricted operations

- Most operations can directly execute on the processor without OS's intervention
- The OS only takes care of protected resources, change running processes or anything that the user program cannot handle properly
- Divide operations into two modes
  - User mode
    - Restricted operations
    - User processes
  - Kernel mode
    - Can perform privileged operations
    - The operating system kernel
- Requires architectural/hardware supports

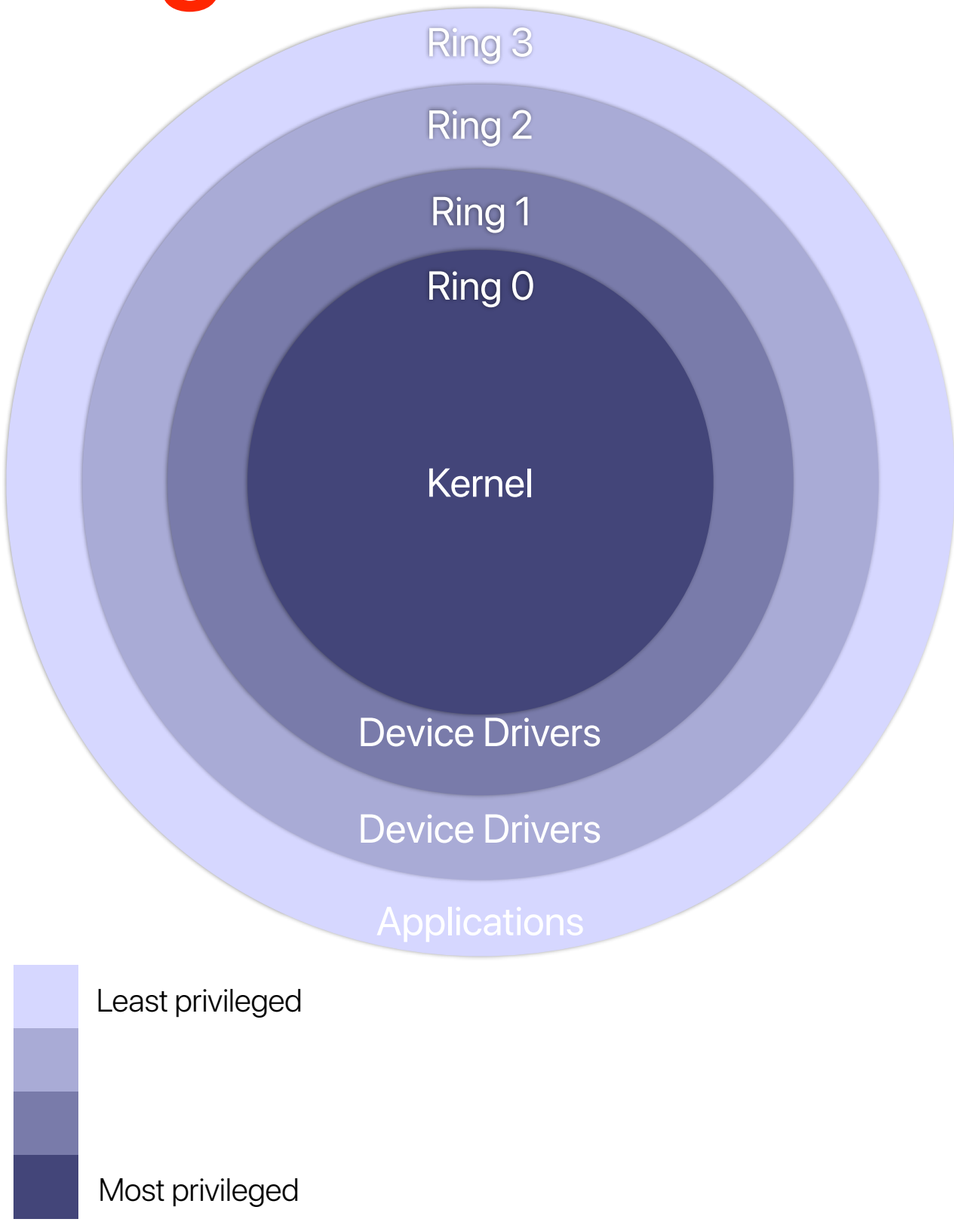
How applications can use privileged operations?

- Through the API: **System calls**
- Implemented in “trap” instructions
  - Raise an exception in the processor
  - The processor saves the exception PC and jumps to the corresponding exception handler in the OS kernel

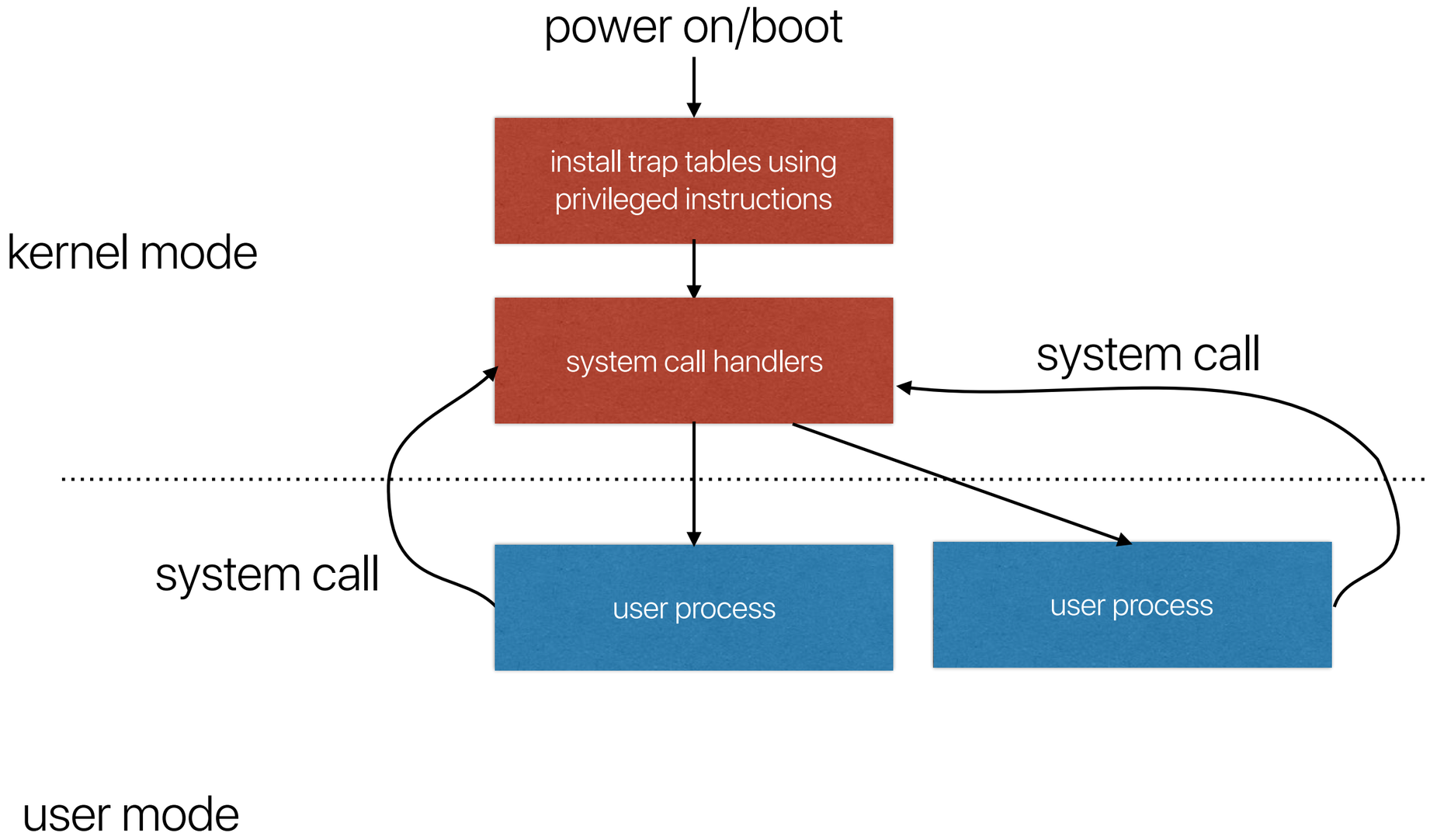


Architectural support: privileged instructions

- The processor provides **normal** instructions and **privileged** instructions
  - Normal instructions: ADD, SUB, MUL, and etc …
  - Privileged instructions: HLT, CLTS, LIDT, LMSW, SIDT, ARPL, and etc…
- The processor provides different modes
  - User processes can use normal instructions
  - Privileged instruction can only be used if the processor is in proper mode



How does the processor knows where to jump to?



Latency Numbers Every Programmer Should Know

Operations	Latency (ns)	Latency (us)	Latency (ms)	
L1 cache reference	0.5 ns			~ 1 CPU cycle
Branch mispredict	5 ns			
L2 cache reference	7 ns			14x L1 cache
Mutex lock/unlock	25 ns			
Main memory reference	100 ns			20x L2 cache, 200x L1 cache
Compress 1K bytes with Zippy	3,000 ns	3 us		
Send 1K bytes over 1 Gbps network	10,000 ns	10 us		
Read 4K randomly from SSD*	150,000 ns	150 us		~1GB/sec SSD
Read 1 MB sequentially from memory	250,000 ns	250 us		
Round trip within same datacenter	500,000 ns	500 us		
Read 1 MB sequentially from SSD*	1,000,000 ns	1,000 us	1 ms	~1GB/sec SSD, 4X memory
Disk seek	10,000,000 ns	10,000 us	10 ms	20x datacenter roundtrip
Read 1 MB sequentially from disk	20,000,000 ns	20,000 us	20 ms	80x memory, 20X SSD
Send packet CA-Netherlands-CA	150,000,000 ns	150,000 us	150 ms	

Demo: Kernel Switch Overhead

- Measure kernel switch overhead using lmbench http://www.bitmover.com/lmbench/