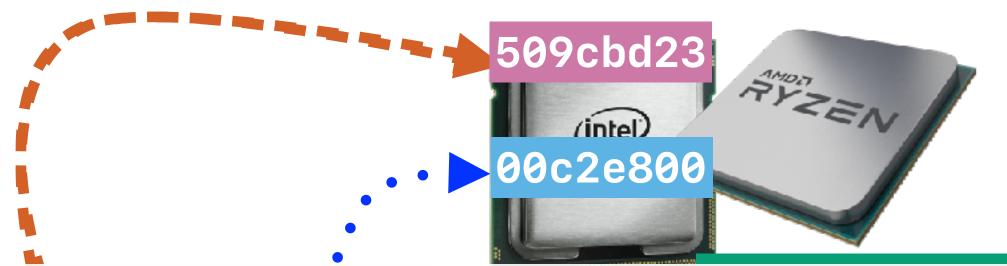
The Fundamentals of Operating Systems

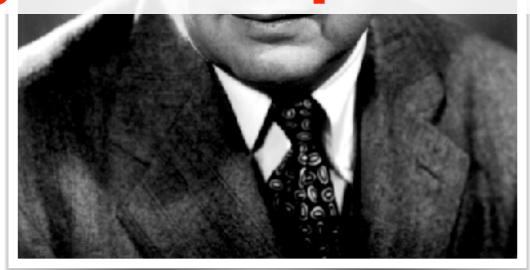
Hung-Wei Tseng

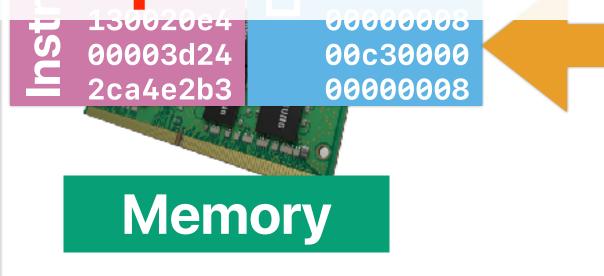
Recap: von Neuman Architecture





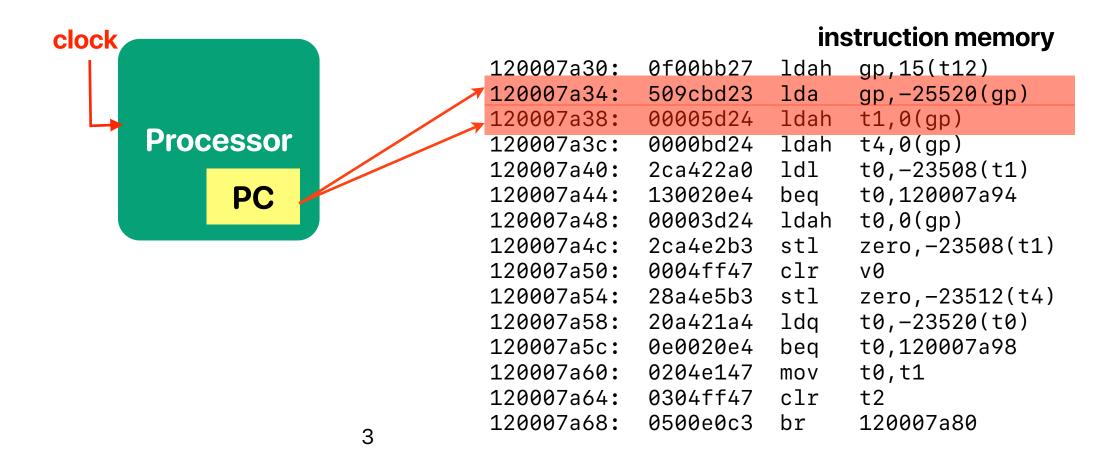
By loading different programs into memory, your computer can perform different functions



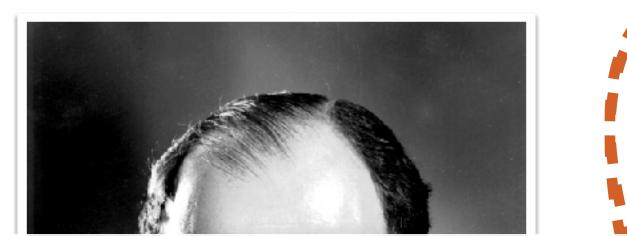


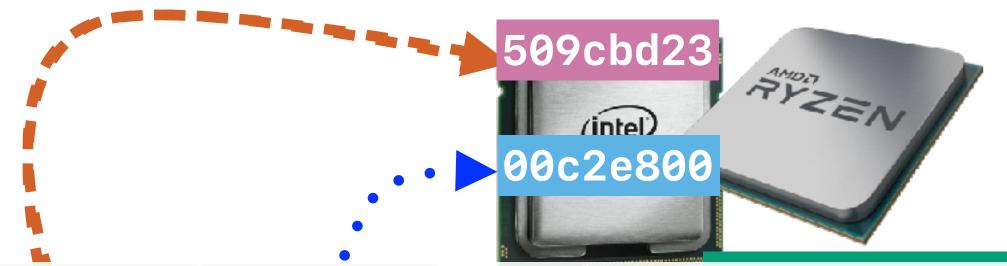
Recap: How processor executes a program

- The program counter (PC) tells where the upcoming instruction is in the memory
- Processor fetches the instruction, decode the instruction, execute the instruction, present the instruction results according to clock signals
- The processor fetches the next instruction whenever it's safe to do so

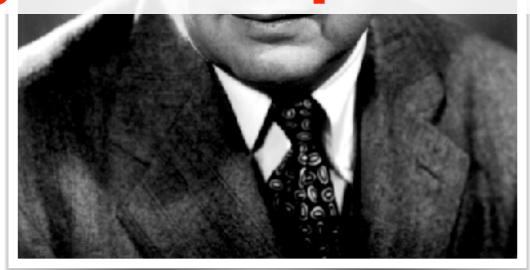


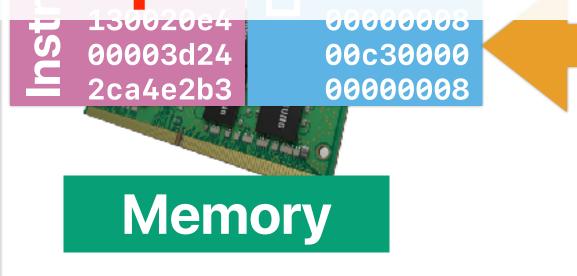
Recap: von Neuman Architecture





By loading different programs into memory, your computer can perform different functions





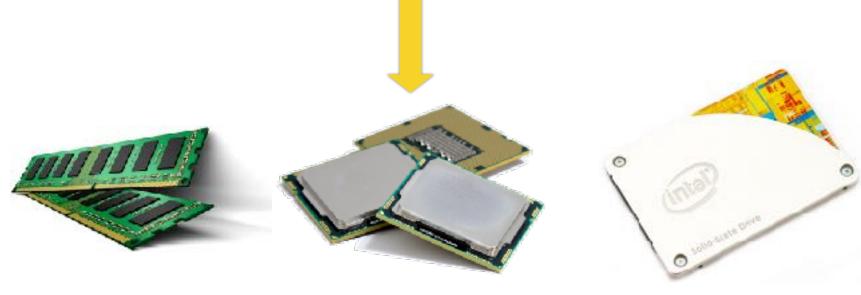




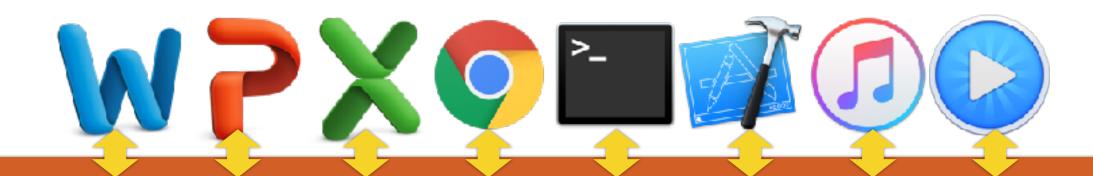
Without an OS: Direct Execution



Only one at a time, no way to interrupt a running task, and etc...



The goal of an OS



Abstraction: Operating System



Recap: What modern operating systems support?

- Virtualize hardware/architectural resources
 - Easy for programs to interact with hardware resources
 - Share hardware resource among programs
 - Protect programs from each other (security)
- Execute multithreaded programs concurrently
 - Support multithreaded programming model
 - Execute multithreaded programs efficiently
- Store data persistently
 - Store data safely
 - Secure

Outline

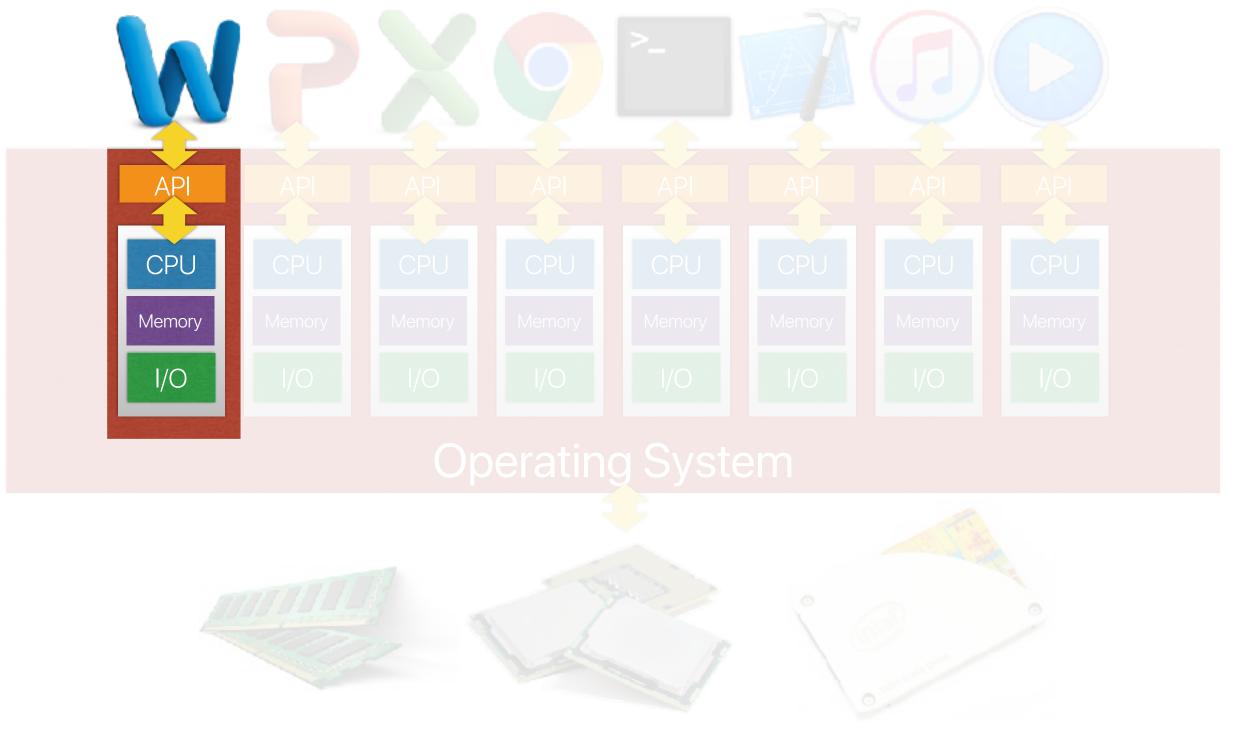
- Operating systems: virtualizing computers
- Process: the most important abstraction in modern OSs
- Restricted operations: kernel and user modes

Operating systems: virtualizing computers

The goal of an OS



The idea of an OS: virtualization



The idea: virtualization

- The operating system presents an illusion of a virtual machine to each running program and maintains architectural states of a von Neumann machine
 - Processor
 - Memory
 - · I/O
- Each virtualized environment accesses architectural facilities through some sort of application programming interface (API)
- Dynamically map those virtualized resources into physical resources

Demo: Virtualization

```
double a;
int main(int argc, char *argv[])
    int cpu, status, i;
    int *address from malloc;
    cpu_set_t my_set;  // Define your cpu_set bit mask.
    CPU_ZERO(&my_set);  // Initialize it all to 0, i.e. no CPUs selected.
    CPU_SET(4, &my_set);
                              // set the bit that represents core 7.
    sched setaffinity(0, sizeof(cpu set t), &my set); // Set affinity of this process to the defined mask, i.e. only 7.
    status = syscall(SYS_getcpu, &cpu, NULL, NULL);
       getcpu system call to retrieve the executing CPU ID
    if(argc < 2)
        fprintf(stderr, "Usage: %s process nickname\n", argv[0]);
        exit(1);
    srand((int)time(NULL)+(int)getpid());
                               create a random number
    a = rand();
   fprintf(stderr, "\nProcess %s is using CPU: %d. Value of a is %lf and address of a is %p\n",argv[1], cpu, a, &a);
    sleep(1);
   fprintf(stderr, "\nProcess %s is using CPU: %d. Value of a is %lf and address of a is %p\n",argv[1], cpu, a, &a);
print the value of a and address of a again after sleep
    sleep(3);
    return 0;
```

Process C	is using	CPU: 4.	Value	of a	is	685161796.000000	and address	of a is 0x6010b0
Process A	is using	CPU: 4.	Value	of a	is	217757257.000000	and address	of a is 0x6010b0
Process B	is using	CPU: 4.	Value	of a	is	2057721479.000000	and address	of a is 0x6010b0
Process D	is using	CPU: 4.	Value	of a	is	1457934803.000000 Different values	and address	of a is 0x6010b0
Process C	is using	CPU: 4.	Value	of a	is	685161796.000000	and address	of a is 0x6010b0
Process A	is using	CPU: 4.	Value	of a	is	217757257.000000	and address	of a is 0x6010b0
Process B	is using	CPU: 4.	Value	of a	is	2057721479.000000	and address	of a is 0x6010b0
Process D	is using	CPU: 4.	Value	of a	is	1457934803.000000	and address	of a is 0x6010b0
	The same processor!					Different values are preserved		The same memory address!

Demo: Virtualization

- Some processes may use the same processor
- Each process has the same address for variable a, but different values.
- You may see the content of a compiled program using objdump

Latency v.s. Throughput

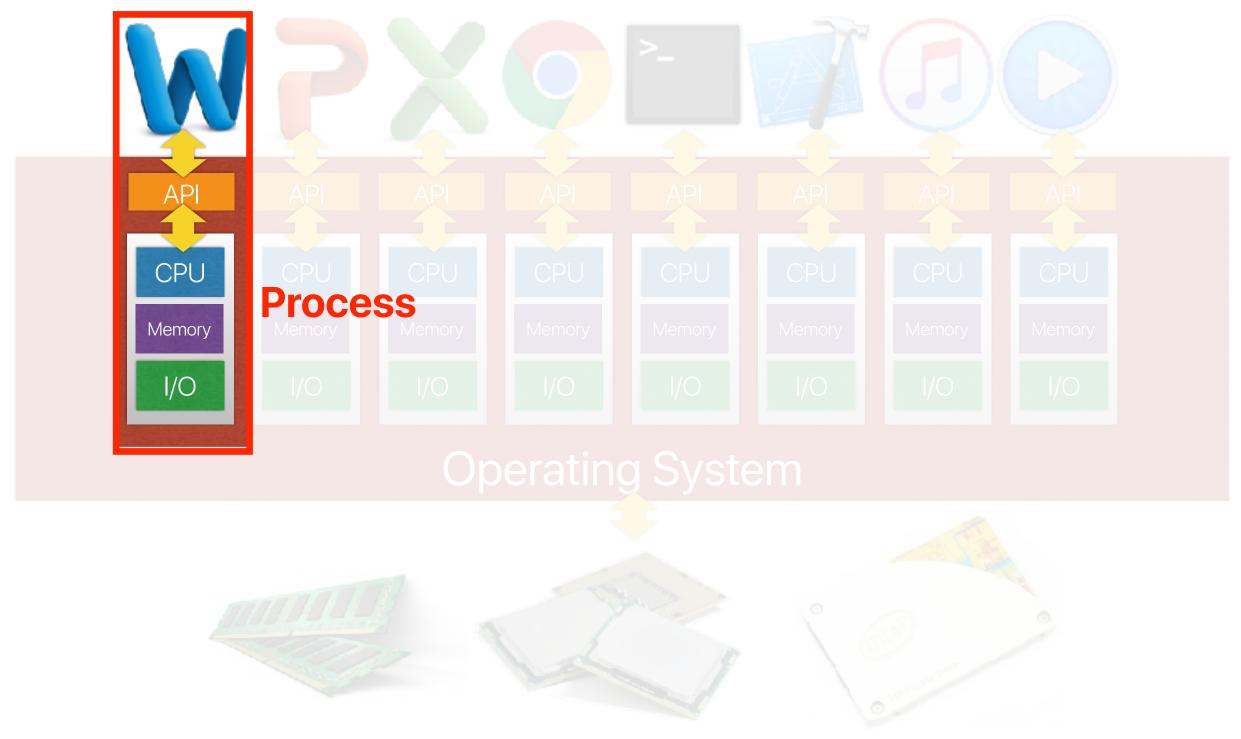
- A 4K movie clip using H.265 coding takes 70GB in storage
- If you want to transfer a total of 2 Peta-Byte video clips (roughly 29959 movies)
 from UCSD
 - 100 miles from UCR
 - Assume that you have a 100Gbps ethernet
 - Throughput: 100 Gbits per second
 - 2 Peta-byte (16 Peta-bits) over 167772 seconds = 1.94 Days
 - Latency: first 70GB (first movie) in 6 seconds

Or ...

	Toyota Prius	10Gb Ethernet
	100 miles from UCSD 75 MPH on highway! 50 MPG Max load: 374 kg = 2,770 hard drives (2TB per drive) = 5.6 PB	
Throughput/ bandwidth	450GB/sec	100 Gb/s or 12.5GB/sec
latency	3.5 hours	2 Peta-byte over 167772 seconds = 1.94 Days
response time	You see nothing in the first 3.5 hours	You can start watching the first movie as soon as you get a frame!

Process: the most important abstraction in modern operating systems

The idea of an OS: virtualization



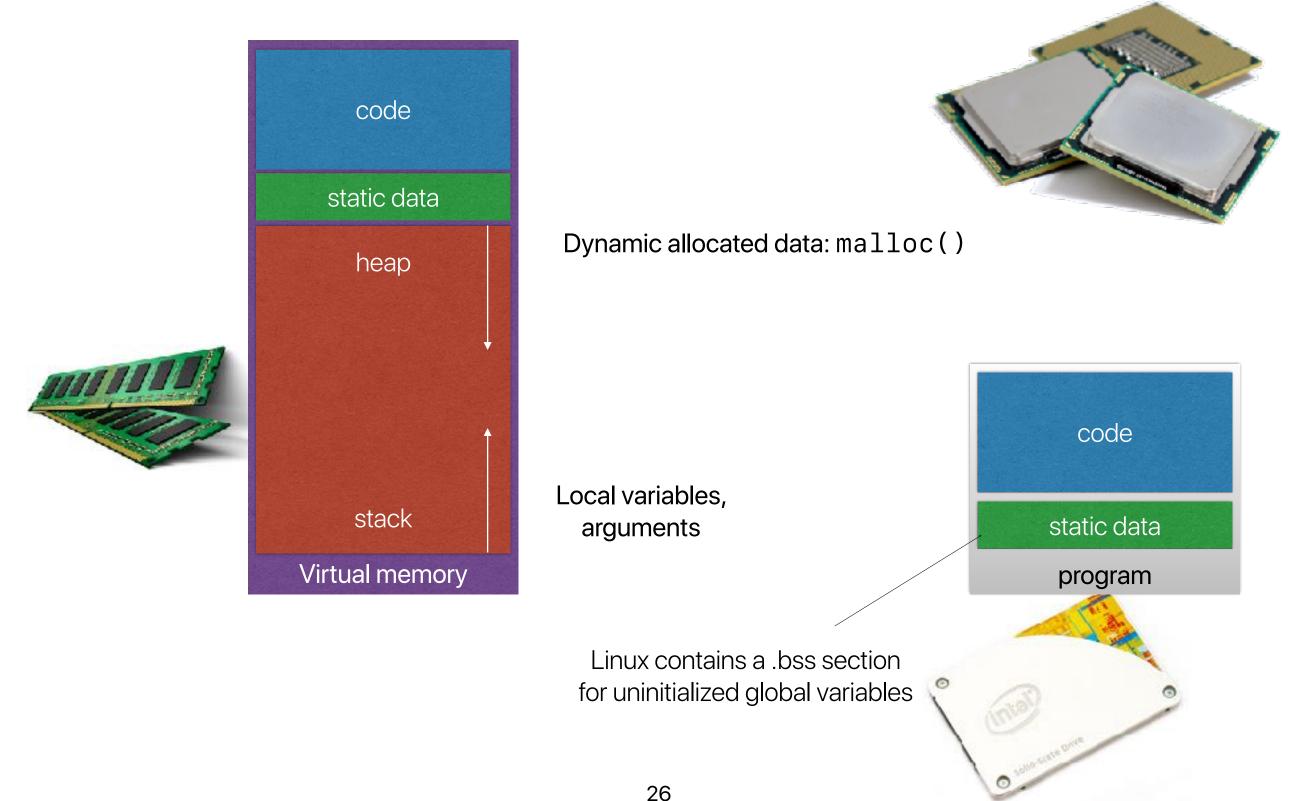
Processes

- The most important abstraction in modern operating systems.
- A process abstracts the underlying computer.
- A process is a running program a dynamic entity of a program.
 - Program is a static file/combination of instructions
 - Process = program + states
 - The states evolves over time
- A process may be dynamically switched out/back during the execution

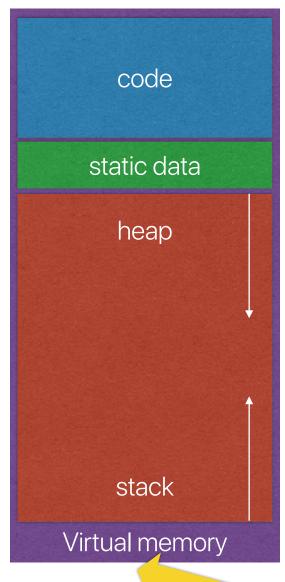
Virtualization

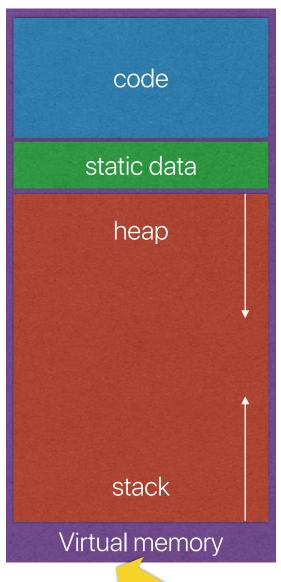
- The operating system presents an illusion of a virtual machine to each running program process
 - Each virtual machine contains architectural states of a von Neumann machine
 - Processor
 - Memory
 - · I/O
- Each virtualized environment accesses architectural facilities through some sort of application programming interface (API)
- Dynamically map those virtualized resources into physical resources policies, mechanisms

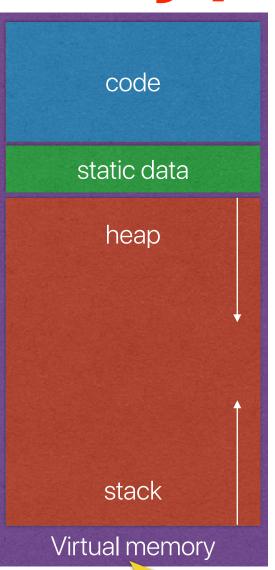
What happens when creating a process

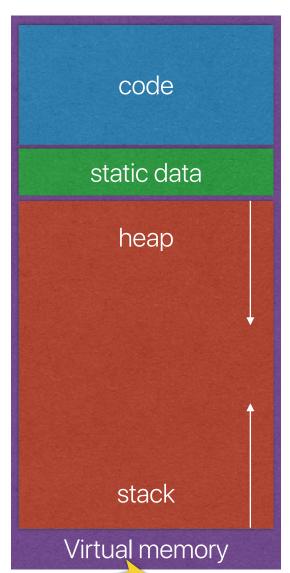


The illusion provided by processes









Virtually, every process seems to have a processor/memory space, but only a few of them are physically executing/using the installed DRAM.

Process control block

- OS has a PCB for each process
- Sometimes called Task Controlling Block, Task Struct, or Switchframe
- The data structure in the operating system kernel containing the information needed to manage a particular process.
- The PCB is the manifestation of a process in an operating system

Example: struct task_struct in Linux

```
Process state
struct task_struct {
                                /* -1 unrunnable, 0 runnable, >0 stopped */
       volatile long state;
        void *stack;
        atomic_t usage;
        unsigned int flags;
                               /* per process flags, defined below */
        unsigned int ptrace;
        int on_rq;
        int prio, static_prio, normal_prio;
        const struct sched_class *sched_class;
        struct sched_entity se;
        struct sched_rt_entity rt;
        unsigned int policy;
        int nr_cpus_allowed;
                                       Process ID
       cpumask_t cpus_allowed;
        pid t pid;
        struct task_struct __rcu *real_parent;
        struct task_struct __rcu *parent;
        struct list_head children;
        struct list_head sibling;
       struct list_nead tasks;
                                       Virtual memory pointers
       struct mm_struct *mm, *active_mm; Low-level architectural states
/* CPU-specific state of this task */
        struct thread_struct thread;
                                             You may find this struct in /usr/src/linux-headers-x.x.x-xx/include/linux/sched.h
```

32

Memory pointers in struct mm_struct

Processor states in struct thread_struct

```
struct thread_struct {
        struct desc_struct tls_array[GDT_ENTRY_TLS_ENTRIES];
        unsigned long
                                 sp0;
        unsigned long
                                 sp;
#ifdef CONFIG X86 32
        unsigned long
                                sysenter_cs;
#else
        unsigned short
                                es;
        unsigned short
                                ds;
        unsigned short
                                 fsindex;
        unsigned short
                                gsindex;
#endif
#ifdef CONFIG X86 32
        unsigned long
                                ip;
#endif
#ifdef CONFIG_X86_64
        unsigned long
                                fs;
#endif
        unsigned long
                                 *ptrace_bps[HBP_NUM];
        struct perf_event
```

Some x86 Register values

Program counter

```
unsigned long
                                     debugreg6;
            unsigned long
                                     ptrace_dr7;
            unsigned long
                                     cr2;
            unsigned long
                                     trap_nr;
            unsigned long
                                     error_code;
#ifdef CONFIG_VM86
            struct vm86
                                     *vm86;
#endif
            unsigned long
                                     *io bitmap ptr;
            unsigned long
                                     iopl;
                                     io bitmap max;
            unsigned
            struct fpu
                                     fpu;
   };
```

Virtualization

However, we don't want everything to pass through this API!



Solution — hardware support

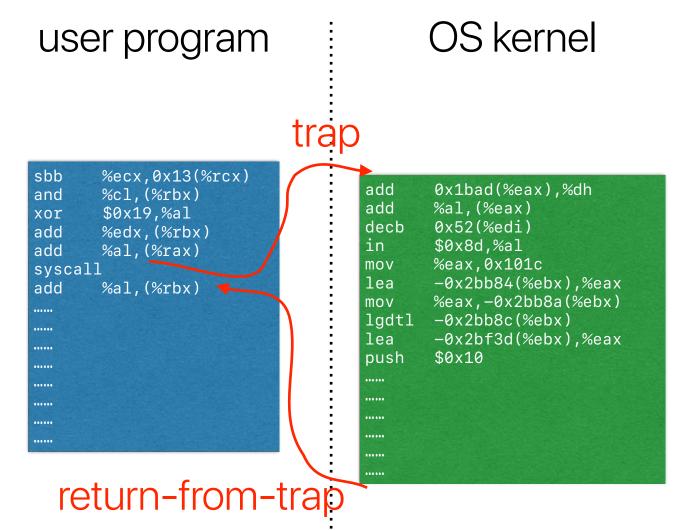
Restricted operations: kernel and user modes

Restricted operations

- Most operations can directly execute on the processor without OS's intervention
- The OS only takes care of protected resources, change running processes or anything that the user program cannot handle properly
- Divide operations into two modes
 - User mode
 - Restricted operations
 - User processes
 - Kernel mode
 - Can perform privileged operations
 - The operating system kernel
- Requires architectural/hardware supports

How applications can use privileged operations?

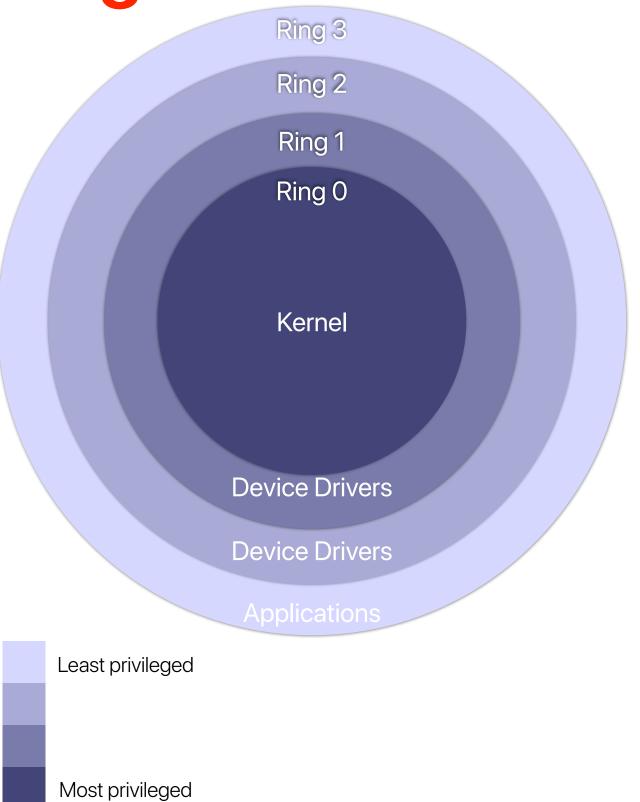
- Through the API: System calls
- Implemented in "trap" instructions
 - Raise an exception in the processor
 - The processor saves the exception PC and jumps to the corresponding exception handler in the OS kernel



user mode kernel/privileged mode

Architectural support: privileged instructions

- The processor provides normal instructions and privileged instructions
 - Normal instructions: ADD, SUB, MUL, and etc ...
 - Privileged instructions: HLT, CLTS, LIDT, LMSW, SIDT, ARPL, and etc...
- The processor provides different modes
 - User processes can use normal instructions
 - Privileged instruction can only be used if the processor is in proper mode



Interrupts, system calls, exceptions

- All of them will trap to kernel mode
- Interrupts: raised by hardware
 - Keystroke, network packets
- System calls: raised by applications
 - Display images, play sounds
- Exceptions: raised by processor itself
 - Divided by zero, unknown memory addresses

"A lie doesn't become truth, wrong doesn't become right and evil doesn't become good, just because it is accepted by a majority."

-RICK WARREN

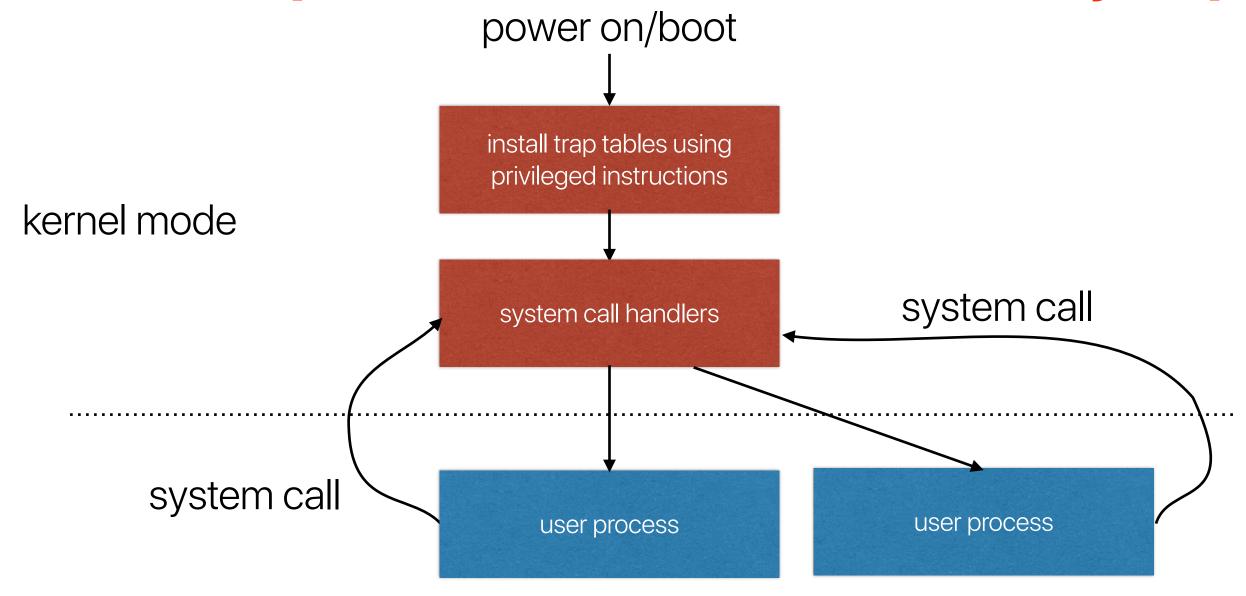
Latency Numbers Every Programmer Should Know

Operations	Latency (ns)	Latency (us)	Latency (ms)	
L1 cache reference	0.5 ns			~ 1 CPU cycle
Branch mispredict	5 ns			
L2 cache reference	7 ns			14x L1 cache
Mutex lock/unlock	25 ns			
Main memory reference	100 ns			20x L2 cache, 200x L1 cache
Compress 1K bytes with Zippy	3,000 ns	3 us		
Send 1K bytes over 1 Gbps network	10,000 ns	10 us		
Read 4K randomly from SSD*	150,000 ns	150 us		~1GB/sec SSD
Read 1 MB sequentially from memory	250,000 ns	250 us		
Round trip within same datacenter	500,000 ns	500 us		
Read 1 MB sequentially from SSD*	1,000,000 ns	1,000 us	1 ms	~1GB/sec SSD, 4X memory
Disk seek	10,000,000 ns	10,000 us	10 ms	20x datacenter roundtrip
Read 1 MB sequentially from disk	20,000,000 ns	20,000 us	20 ms	80x memory, 20X SSD
Send packet CA-Netherlands-CA	150,000,000 ns	150,000 us	150 ms	

Demo: Kernel Switch Overhead

Measure kernel switch overhead using Imbench http://www.bitmover.com/Imbench/

How does the processor knows where to jump to?



user mode

Context Switch

- The process of changing the running program on a processor
- What happen during context switches:
 - Save the current architectural context in the memory
 - Execute machine dependent assembly code to save register values to memory
 - Restore the architectural context for the new running process
 - Execute machine dependent assembly code to load register values to memory
 - Jump to the PC of the new running process

Latency Numbers Every Programmer Should Know

Operations	Latency (ns)	Latency (us)	Latency (ms)	
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Send packet CA-Netherlands-CA	150,000,000 ns	150,000 us	150 ms	

Announcement

- Two reading quizzes next week
 - We will discuss 4 papers next week
 - We split them into two since that's probably the first you read papers